

# Alternative Statistical Model: Weighted Least Square and Generalized Least Square

Xingye Qiao  
Dr. Jim Crooks

SAMSI  
SAMSI/CRSC Undergraduate Workshop at NCSU

May 22, 2007

## Outline

- 1 Introduction**
  - Recall of Ordinary Least-Square Regression
  - Current Model
  
- 2 Improved Model**
  - Weighted Least-Square
  - Generalized Least-Square

# Outline

- 1 Introduction**
  - Recall of Ordinary Least-Square Regression
  - Current Model
  
- 2 Improved Model**
  - Weighted Least-Square
  - Generalized Least-Square

# Least Square Regression

- Linear
  - “Linear” is for the parameter(s)
  - e.g.  $y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$

# Least Square Regression

- Linear
  - “Linear” is for the parameter(s)
  - e.g.  $y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$
- Non-linear
  - “Non-linear” is for the parameter(s)
  - e.g.  $y_i = \exp(-\beta_1 x_i) + \alpha \cos(\beta_2 x_i) + \varepsilon_i$

# Least Square Regression

- Linear
  - “Linear” is for the parameter(s)
  - e.g.  $y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$
- Non-linear
  - “Non-linear” is for the parameter(s)
  - e.g.  $y_i = \exp(-\beta_1 x_i) + \alpha \cos(\beta_2 x_i) + \varepsilon_i$
- Summary
  - $y_i = \eta(x_i; \beta) + \varepsilon_i$
  - $\eta(x; \beta)$  is deterministic function of  $x$ , with parameter  $\beta$
  - **Goal: to estimate parameter  $\beta$**

# OLS estimation

- Find  $\beta$  to minimize

$$\sum_{i=1}^m (y_i - \eta(x_i; \beta))^2,$$

to give  $\hat{\beta}_{OLS}$

- **Standard Statistical Assumption:**
  - Mean of  $\varepsilon_i$  is 0 for all  $i$
  - Variance of  $\varepsilon_i$  is constant for all  $i$ , equal to  $\sigma^2$
  - $\varepsilon_i, \varepsilon_j$  are independent of each other for all  $i \neq j$

## OLS Estimation (Cont.)

### Property of OLS Estimation

- $\hat{\beta}_{OLS}$  converges to  $\beta$  as  $n$  increases

## OLS Estimation (Cont.)

### Property of OLS Estimation

- $\hat{\beta}_{OLS}$  converges to  $\beta$  as  $n$  increases
- Makes efficient use of the data, i.e. has small standard error

## OLS Estimation (Cont.)

### Property of OLS Estimation

- $\hat{\beta}_{OLS}$  converges to  $\beta$  as  $n$  increases
- Makes efficient use of the data, i.e. has small standard error
- These properties hold only when **the model is a right model**. To be more specific, when **the standard statistical assumption holds**.

## Inverse Problem

- Spring Model:

$$\frac{d^2y(t)}{dt^2} + C\frac{dy(t)}{dt} + Ky(t) = 0$$

## Inverse Problem

- Spring Model:

$$\frac{d^2y(t)}{dt^2} + C\frac{dy(t)}{dt} + Ky(t) = 0$$

- For each given C and K, the differential equation has a unique solution given initial value, called  $y(t; C, K)$

## Inverse Problem

- Spring Model:

$$\frac{d^2y(t)}{dt^2} + C\frac{dy(t)}{dt} + Ky(t) = 0$$

- For each given C and K, the differential equation has a unique solution given initial value, called  $y(t; C, K)$
- Target: Estimate C and K based on the observed  $y_i$

## Inverse Problem

- Spring Model:

$$\frac{d^2y(t)}{dt^2} + C\frac{dy(t)}{dt} + Ky(t) = 0$$

- For each given C and K, the differential equation has a unique solution given initial value, called  $y(t; C, K)$
- Target: Estimate C and K based on the observed  $y_i$
- Minimize the cost function

$$L(C, K) = \sum_{i=1}^m (y_i - y(t_i; C, K))^2$$

## Underlying Statistical Models

- The above model can be viewed as a regression model

$$y_i = y(t_i; C, K) + \varepsilon_i$$

- Here  $\varepsilon_i$  are iid (independent identically distributed) from  $N(0, \sigma^2)$ . That is we suppose the **statistical assumptions** hold.

## Underlying Statistical Models

- The above model can be viewed as a regression model

$$y_i = y(t_i; C, K) + \varepsilon_i$$

- Here  $\varepsilon_i$  are iid (independent identically distributed) from  $N(0, \sigma^2)$ . That is we suppose the **statistical assumptions** hold.
- **But is this model a right model?**

## Violation of Statistical Assumptions

- 1 Is variance of  $\varepsilon_j$  constant across time range?

## Violation of Statistical Assumptions

- 1 Is variance of  $\varepsilon_j$  constant across time range?
- 2 Are error independent?

## Violation of Statistical Assumptions

- 1 Is variance of  $\varepsilon_i$  constant across time range?
- 2 Are error independent?
- 3 Are error from  $N(0, \sigma^2)$ ?

## Violation of Statistical Assumptions

- 1 Is variance of  $\varepsilon_i$  constant across time range?
- 2 Are error independent?
- 3 Are error from  $N(0, \sigma^2)$ ?

Implication:

## Violation of Statistical Assumptions

- 1 Is variance of  $\varepsilon_i$  constant across time range?
- 2 Are error independent?
- 3 Are error from  $N(0, \sigma^2)$ ?

Implication:

- Standard statistical assumptions don't hold.

## Violation of Statistical Assumptions

- 1 Is variance of  $\varepsilon_i$  constant across time range?
- 2 Are error independent?
- 3 Are error from  $N(0, \sigma^2)$ ?

Implication:

- Standard statistical assumptions don't hold.
- $[\hat{C}, \hat{K}]$  are no longer good estimators for  $[C, K]$ .

## Violation of Statistical Assumptions

- 1 Is variance of  $\varepsilon_i$  constant across time range?
- 2 Are error independent?
- 3 Are error from  $N(0, \sigma^2)$ ?

Implication:

- Standard statistical assumptions don't hold.
- $[\hat{C}, \hat{K}]$  are no longer good estimators for  $[C, K]$ .
- We should find a way to remedy this problem.

## Outline

- 1 **Introduction**
  - Recall of Ordinary Least-Square Regression
  - Current Model
- 2 **Improved Model**
  - Weighted Least-Square
  - Generalized Least-Square

# Assumption

- Instead of constant variance assumption, we deal with nonconstant variance here.

# Assumption

- Instead of constant variance assumption, we deal with nonconstant variance here.
- Assume  $Var(\varepsilon_i) = \frac{\sigma^2}{w_i}, i = 1, \dots, m$ , for known  $w_i$

# Assumption

- Instead of constant variance assumption, we deal with nonconstant variance here.
- Assume  $Var(\varepsilon_i) = \frac{\sigma^2}{w_i}, i = 1, \dots, m$ , for known  $w_i$
- What does it mean for  $(y_i, t_i)$  if  $w_i$  is large?

# Assumption

- Instead of constant variance assumption, we deal with nonconstant variance here.
- Assume  $Var(\varepsilon_i) = \frac{\sigma^2}{w_i}, i = 1, \dots, m$ , for known  $w_i$
- What does it mean for  $(y_i, t_i)$  if  $w_i$  is large?
  - $\Leftrightarrow$  This observation is of high quality.

# Assumption

- Instead of constant variance assumption, we deal with nonconstant variance here.
- Assume  $Var(\varepsilon_i) = \frac{\sigma^2}{w_i}, i = 1, \dots, m$ , for known  $w_i$
- What does it mean for  $(y_i, t_i)$  if  $w_i$  is large?
  - $\Leftrightarrow$  This observation is of high quality.
  - $\Leftrightarrow$  This observation is of importance

# Solve Weighted Least Square in Linear Case

Consider linear context,

$$y_i = x_i^T \beta + \varepsilon_i.$$

# Solve Weighted Least Square in Linear Case

Consider linear context,

$$y_i = x_i^T \beta + \varepsilon_i.$$

Denote

$$y_i^* = \sqrt{w_i} y_i, x_i^* = \sqrt{w_i} x_i,$$

## Solve Weighted Least Square in Linear Case

Consider linear context,

$$y_i = x_i^T \beta + \varepsilon_i.$$

Denote

$$y_i^* = \sqrt{w_i} y_i, x_i^* = \sqrt{w_i} x_i,$$

Then

$$y_i^* = x_i^{*T} \beta + \sqrt{w_i} \varepsilon_i,$$

where  $\text{Var}(\sqrt{w_i} \varepsilon_i) = w_i \text{Var}(\varepsilon_i) = \sigma^2$

## Solve Weighted Least Square in Linear Case (Cont.)

Then minimizing the weighted (least) sum squares of error

$$S = \sum_{i=1}^n w_i (y_i - x_i^T \beta)^2,$$

is the same as minimizing the ordinary (least) sum squares of error

$$S = \sum_{i=1}^n (y_i^* - x_i^{*T} \beta)^2.$$

## Solve Weighted Least Square in Linear Case (Cont.)

Then minimizing the weighted (least) sum squares of error

$$S = \sum_{i=1}^n w_i (y_i - x_i^T \beta)^2,$$

is the same as minimizing the ordinary (least) sum squares of error

$$S = \sum_{i=1}^n (y_i^* - x_i^{*T} \beta)^2.$$

In matrix notation, the weighted least squares estimator of  $\beta$  is

$$\hat{\beta} = (X^{*T} X^*)^{-1} X^{*T} Y^* = (X^T W X)^{-1} X^T W Y, \quad W = \text{diag}\{w_1, \dots, w_n\}.$$

## Estimation

- Instead of minimizing  $\sum_{i=1}^m (y_i - y(t_i; C, K))^2$  in OLS, here minimize

$$\tilde{L}(C, K) = \sum_{i=1}^m w_i (y_i - y(t_i; C, K))^2,$$

to give  $\hat{C}$  and  $\hat{K}$

## Value of $w_j$

- In practice, we don't know  $w_j$ . Several ways to estimate  $w_j$ :

## Value of $w_i$

- In practice, we don't know  $w_i$ . Several ways to estimate  $w_i$ :
  - 1 Estimate  $\text{Var}(\varepsilon_i)$  as  $\hat{\sigma}_i^2$  from repeated measurement at time  $t_i$ :

$$w_i = \frac{\sigma^2}{\hat{\sigma}_i^2}.$$

## Value of $w_i$

- In practice, we don't know  $w_i$ . Several ways to estimate  $w_i$ :
  - 1 Estimate  $Var(\varepsilon_i)$  as  $\hat{\sigma}_i^2$  from repeated measurement at time  $t_i$ :

$$w_i = \frac{\sigma^2}{\hat{\sigma}_i^2}.$$

- 2 If error is larger for larger  $|y_i|$ , simply let  $w_i = \frac{1}{y_i^2}$

## Value of $w_i$

- In practice, we don't know  $w_i$ . Several ways to estimate  $w_i$ :
  - 1 Estimate  $Var(\varepsilon_i)$  as  $\hat{\sigma}_i^2$  from repeated measurement at time  $t_i$ :

$$w_i = \frac{\sigma^2}{\hat{\sigma}_i^2}.$$

- 2 If error is larger for larger  $|y_i|$ , simply let  $w_i = \frac{1}{y_i^2}$
- 3 Or, alternatively, assume that  $w_i = \frac{1}{y^2(t_i; C, K)}$

## Assumption

More general, now deal with correlated observations and nonconstant variance (weighted least square only deals with nonconstant variance):

## Assumption

More general, now deal with correlated observations and nonconstant variance (weighted least square only deals with nonconstant variance):

- Let  $\varepsilon = (\varepsilon_1, \varepsilon_2, \dots, \varepsilon_m)^T$ , and assume

$$\text{Cov}(\varepsilon) = \sigma^2 V, \text{ for known matrix } V.$$

## Assumption

More general, now deal with correlated observations and nonconstant variance (weighted least square only deals with nonconstant variance):

- Let  $\varepsilon = (\varepsilon_1, \varepsilon_2, \dots, \varepsilon_m)^T$ , and assume

$$\text{Cov}(\varepsilon) = \sigma^2 V, \text{ for known matrix } V.$$

- Let  $W = V^{-1}$ . Remember that if  $V$  is diagonal matrix, then this is the case in weighted least square, and  $W = \text{diag}\{w_1, w_2, \dots, w_m\}$ .

# Estimation

- The generalized Least Square estimator minimizes

$$\tilde{L}(C, K) = \{y - y(t; C, K)\}^T W \{y - y(t; C, K)\},$$

to given  $\hat{C}$  and  $\hat{K}$ .

# Estimation

- The generalized Least Square estimator minimizes

$$\tilde{L}(C, K) = \{y - y(t; C, K)\}^T W \{y - y(t; C, K)\},$$

to given  $\hat{C}$  and  $\hat{K}$ .

- If the proposed covariance model holds, then the estimators have good properties.

## Anything More?

- Does this improved model work better?

## Anything More?

- Does this improved model work better?
- If not, what might be the main problem?

## Anything More?

- Does this improved model work better?
- If not, what might be the main problem?
- Let Jim take over.